

## 1. Ranges of parameters visible on UI

Table 1 UI parameters

Name	Symbol	Range			
		(mm)	(in)	(°)	-
module	$m$	0.5 ... 20	0.03125 ... 1		
pressure angle	$\alpha$			14.5 ... 25	
clearance factor	$f_c$				0.1 ... 0.25 <sup>(2)</sup>
thickness	$t$	0.5 ... 1000	0.03125 ... 40		
helix angle	$\beta$			10 ... 40	
groove width	$g_w$	0.5 ... 960 <sup>(1)</sup>	0.03125 ... 38 <sup>(1)</sup>		
groove depth	$g_d$	0.1 ... 10000 <sup>(1)</sup>	0.00781 ... 400 <sup>(1)</sup>		
teeth number	$z_1, z_2$				6 ... 200 <sup>(3)</sup>
profile shift factor	$x_1, x_2$				-0.7 ... 1 <sup>(2, 4)</sup>
taper factor	$f_{t1}, f_{t2}$				0 ... 0.5 <sup>(2, 5)</sup>
backlash (linear)	$j_1, j_2$	-0.2 ... 0.2	-0.01563 ... 0.01563		
chamfer width factor	$f_{cw}$				0.1 ... 0.25 <sup>(2)</sup>
chamfer height factor	$f_{ch}$				0.1 ... 0.25 <sup>(2)</sup>
X-coordinate of wheel's center	$dX$	-6100 ... 6100 <sup>(6)</sup>	-310 ... 310 <sup>(6)</sup>		
Y-coordinate of wheel's center	$dY$	-6100 ... 6100 <sup>(6)</sup>	-310 ... 310 <sup>(6)</sup>		
wheel orientation angle	$\gamma$			0 ... 360	

- (1) Visible for double helical gears; range can be also limited by thickness or root diameter,
- (2) related to module,
- (3) in case of external-internal or internal-external pair, teeth number of internal gear will be automatically changed if it is less than in external gear,
- (4) when automatically calculated (manual center distance) external gear's factor will be 0,
- (5) enabled for external gears,
- (6) they are edge limits; practically, range is strongly dependent of module, number of teeth, type of gears and type of tooth view; algorithm for calculating profiles automatically accepts only reasonable values, slightly different than basic  $dX$ ,  $dY$  numbers for given settings.

The subscripts 1 and 2 denote pinion and wheel.

## 2. Parameters visible in 3<sup>rd</sup> mode of preview

Table 2 3<sup>rd</sup> mode parameters

Symbol	Meaning
$z$	number of teeth
$d_w$	working pitch diameter
$d_b$	base diameter
$d_f$	root diameter
$d_a$	outside diameter
$\alpha_w$	working pressure angle
$a$	center distance
$dX$	X-coordinate of wheel's center <sup>(1)</sup>
$dY$	Y-coordinate of wheel's center <sup>(1)</sup>
$\gamma$	wheel orientation angle <sup>(1)</sup>
$dir.$	teeth direction <sup>(2)</sup>

(1) Visible only for wheel,

(2) right/left, only for non-straight teeth.

### 3. Information saved in components

Table 3 Components' information

Group	Symbol	Meaning
Radial parameters	$d$	pitch diameter
	$d_w$	working pitch diameter
	$d_b$	base diameter
	$d_f$	root diameter
	$d_a$	outside diameter
	$x$	profile shift factor
	$f_t$	taper factor
	$j$	backlash
	$\alpha_w$	working pressure angle
	$a$	center distance
Land parameters <sup>(1)</sup>	$\alpha_a$	pressure angle at outside diameter
	$\theta$	half of top land angle at outside diameter
	$s_a$	top land thickness
Motion link formulas	<i>pinion (i) wheel (o)</i>	formula when pinion is the driving gear
	<i>pinion (o) wheel (i)</i>	formula when wheel is the driving gear
Ratio	$\eta$	ratio of pinion to wheel
Placement and rotation <sup>(2)</sup>	$dX$	X-coordinate of wheel's center
	$dY$	Y-coordinate of wheel's center
	$\gamma$	wheel orientation angle (around pinion's axis)
	$\delta$	wheel rotation angle (around its own axis)

(1) Visible only for external gears,

(2) visible only for wheel.